

University of California Berkeley

Department of Electrical Engineering and Computer Science

Watertight Planar Surface Meshing of Indoor Point-Clouds with Voxel Carving

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Goal

Create triangulated meshes that represents the geometry of a point-cloud.

- Watertight representation
- Memory efficient processing and representation
- Handle large point-clouds (over 100 million points)
- Generate planar models
- Ensure high-quality triangles
- Preserve fine detail

Motivation

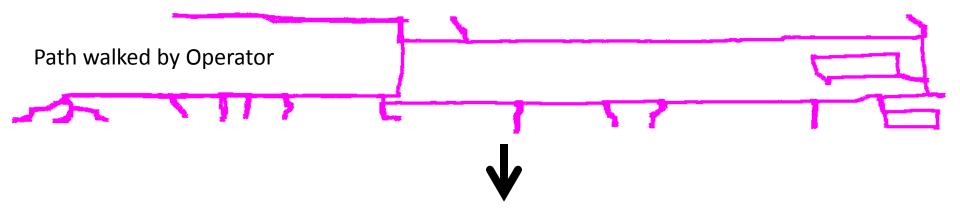
- Virtual walkthroughs
- Indoor navigation
- Augmented reality
- Energy simulation applications

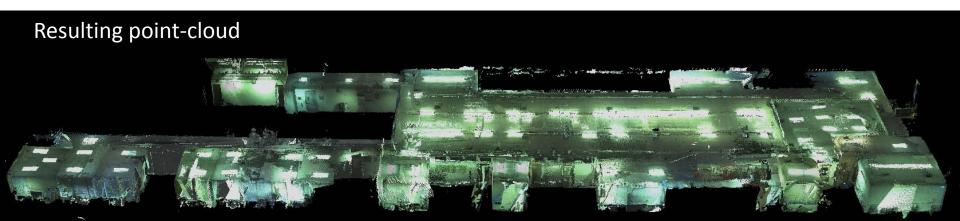
Input Data

Input point-cloud created using ambulatory scanning system, mounted on a human operator as a backpack.

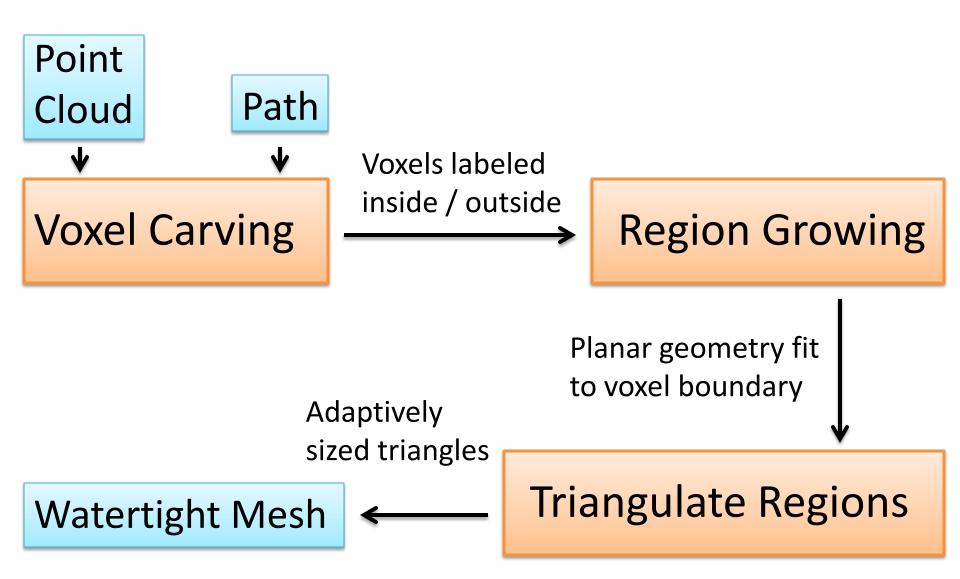


Localizing system during data collection enables tracking the path of the backpack to generate a point-cloud from the collected LiDAR scans.





Surface Meshing System Diagram

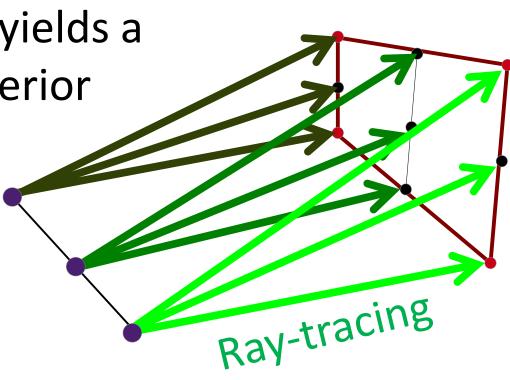


Carving

The line segment between each scan point and the scanner position represents open space Path of Scanner LiDAR points

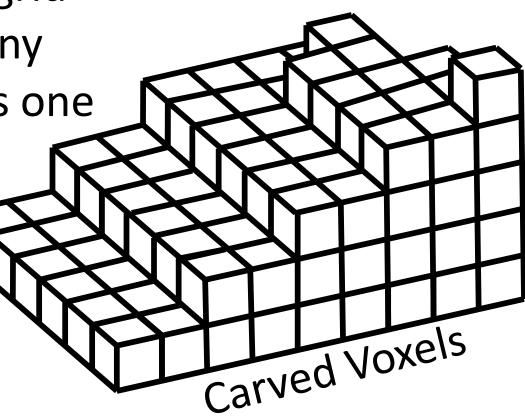
Carving

Interpolating a solid volume between these lines yields a representation of interior space



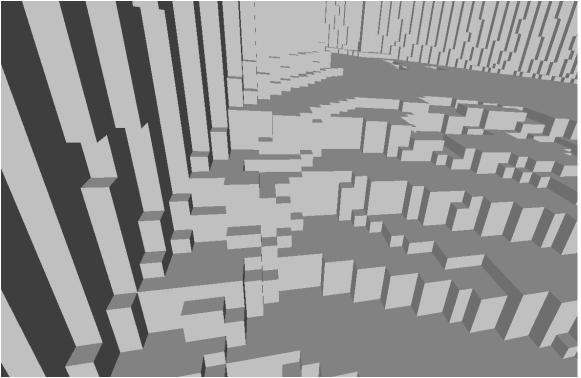
Carving

By defining a voxel grid in space, we label any voxel that intersects one of these lines to be *interior*, and the rest are *exterior*



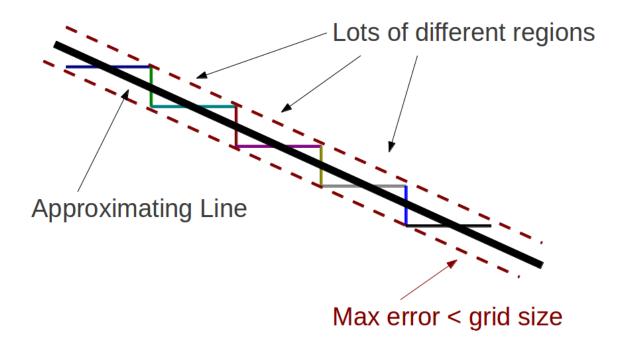
Plane Fitting

Carved voxels of staircase



Surface of voxels is descretized. Want to fit planes to remove "zig-zag" artifacts

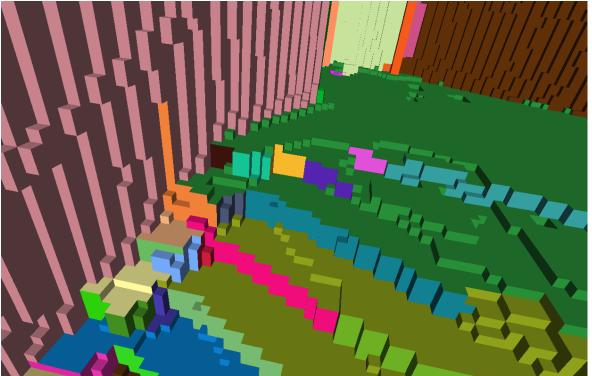
Plane Fitting



Iteratively group regions that well-represent planes

Plane Fitting

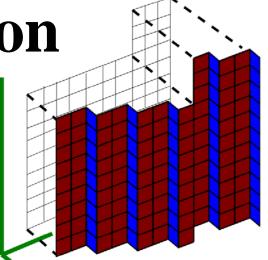
Grown planar regions

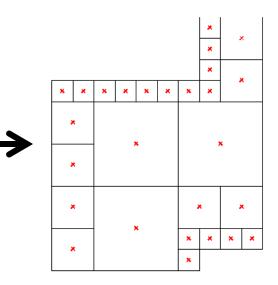


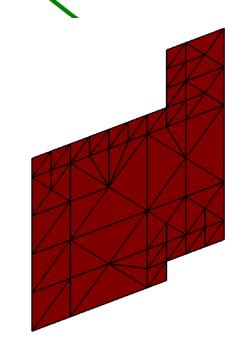
Voxel faces are grouped into regions that are approximately planar

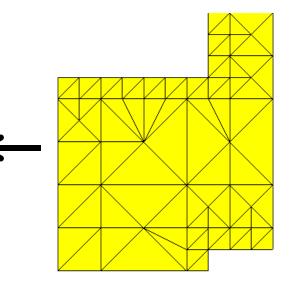
Triangulation

- Voxel faces grouped into regions, but still discretized
- Each region is triangulated along its dominant axis
- Triangulation uses a quadtree structure to adaptively mesh each region, so larger regions use larger triangles
- The triangulations are merged into a 3D mesh so the seams are watertight

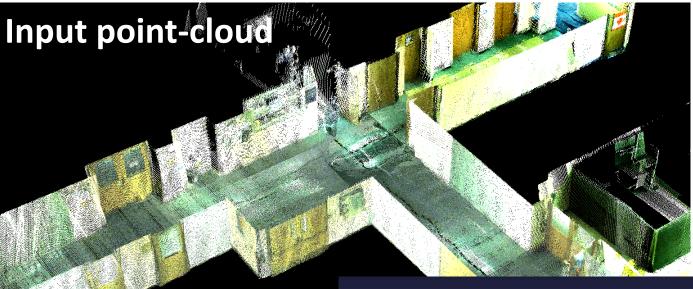








Results



Output mesh

Model of conference room

Input point-cloud

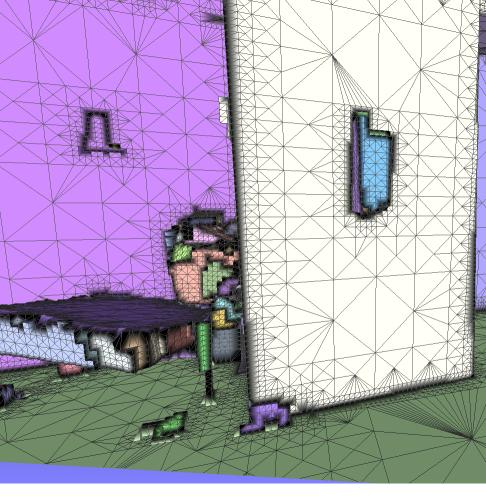
Triangulation

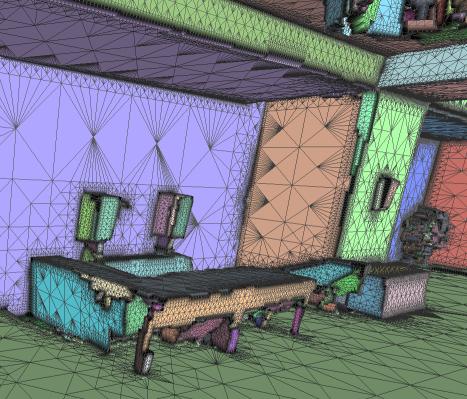
Model of hotel hallways

Input point-cloud

SULICIE

Triangulation





Mesh, colored by region

Point-cloud

Close up of hotel hallway

Viewing triangulation and planar regions

Constructed mesh of hallway

BUI

Texture-mapped mesh of hallway